

Web Images Video News Maps Gmail more ▾

Sign in

Google

multi-joint robot with two tools and interpolation

Search

Advanced Search
Preferences

The "AND" operator is unnecessary -- we include all search terms by default. [View details](#)

Web Results 1 - 10 of about 333 for **multi-joint robot with two tools and interpolation**. (0.38 seconds)

Multi-joint robot and control device thereof - Patent 20050204848

1 in this way, a handling system by the **robot** having **two tools** at a single unit ... a position and an attitude of the **tool** such as linear **interpolation**. ...

www.freepatentsonline.com/20050204848.html - 34k - [Cached](#) - [Similar pages](#)

Robot bus architecture with distributed electronics - Patent 5130631

In a **multi-joint robot** having at least **two** joints dispersed away from a central processor as described above requires decomposition, or **interpolation**, ...

www.freepatentsonline.com/5130631.html - 40k - [Cached](#) - [Similar pages](#)

[[More results from www.freepatentsonline.com](#)]

Method of controlling robot movements - US Patent 5157315

Method for positioning a **tool** of a **multi-joint robot** Issued on: January 16, ... reading orientation values at initial and terminal **interpolation** points; ...

www.patentstorm.us/patents/5157315-claims.html - 51k - [Cached](#) - [Similar pages](#)

Method of controlling articulated robot - US Patent 5187418

Method for positioning a **tool** of a **multi-joint robot** ... The first control point is controlled by way of **interpolation**, and the second control point is ...

www.patentstorm.us/patents/5187418-description.html - 24k - [Cached](#) - [Similar pages](#)

[[More results from www.patentstorm.us](#)]

>>From: srctran@world.std.com (Gregory Aharonian) Newsgroups: comp ...

Method for positioning a **tool** of a **multi-joint robot** Locus **interpolation** device . Neural network system for adaptive sensory-motor coordination of ...

www.mirrorservice.org/sites/athena-dist.mit.edu/pub/lpf/ai.patent.list - 20k -

[Cached](#) - [Similar pages](#)

[PDF] A multifunctional dual-arm edurobot

File Format: PDF/Adobe Acrobat

2.1 Summary. The **robot** adopts a **multijoint** structure, and the key parts of it are. **two** plane arms, each of which consists of a forearm and an upper ...

www.springerlink.com/index/OUXV4B0T95WC3V95.pdf - [Similar pages](#)

[PDF] A robot test-bed for assistance and assessment in physical therapy

File Format: PDF/Adobe Acrobat

the human arm to interact with the **robot** in **two** modes: (1) passive (P) and N. Hogan,

The mechanics of **multi-joint** posture and movement control, Biol. ...

www.springerlink.com/index/MQ1J164087623X22.pdf - [Similar pages](#)

[PDF] Mechatronics and robotics in Europe - Industrial Electronics ...

File Format: PDF/Adobe Acrobat

introduction of innovative **tools** for advanced production planning. purposes. Advanced **multi-joint robot** Jystem for the production of complex ...

ieeexplore.ieee.org/iel2/1044/7958/00339115.pdf?arnumber=339115 - [Similar pages](#)

[PDF] A Motion Planning Algorithm for Redundant Kinematic Structure ...

File Format: PDF/Adobe Acrobat

criteria and **multi-joint** stability criteria separately. (a) For single joint motion experiment with a **two-armed space robot**", Proc. IEEE ...
ieeexplore.ieee.org/iel3/4016/11534/00527565.pdf?arnumber=527565 - Similar pages

ScienceDirect - Mechatronics : An effective **robot** trajectory ...

In this method, a polynomial based on Hermite cubic **interpolation** is applied to Yano F, Tooda Y. Preferable movement of a **multi-joint robot** arm using ...
linkinghub.elsevier.com/retrieve/pii/S0957415803000990 - Similar pages

[1](#) [2](#) [3](#) [4](#) [5](#) [6](#) [7](#) [8](#) [9](#) [10](#) **Next**

Download [Google Pack](#): free essential software for your PC

[Search within results](#) | [Language Tools](#) | [Search Tips](#) | [Dissatisfied? Help us improve](#)

©2007 Google - [Google Home](#) - [Advertising Programs](#) - [Business Solutions](#) - [About Google](#)